ANALYSIS OF STATICAL ANALYSIS ON INTEGRATED BUILDING OF STEEL STRUCTURES WITH WIND TURBINES

Abhijit Palit¹, Dr. Pankaj Singh²

¹Research Scholar, Department of Civil Engineering, Faculty of Engineering, SRK University, M.P. India ²Professor, Department of Civil Engineering, Faculty of Engineering, SRK University, M.P. India

ABSTRACT

The wind turbines are fully modeled using modeling Software's SOLIDWORKS. And the majority of the shape analysis of the tower was performed the use of the finite element method (FEM). Using Abaqus, industrial FEM software, both static and dynamic structural analyses had been performed. A simplified finite element model that represents the wind turbine tower was once created the usage of beam, shell, and inertia elements. An ultimate load condition was once applied to take a look at the stress stage of the tower in the static analysis. For the dynamic analysis, the frequency extraction was once carried out in order to acquire the natural frequencies and the mode shapes of the tower. Using the results, the response spectrum evaluation and the transient dynamic analysis, which are primarily based on the modal superposition method, have been performed in order to see the structure's response for earthquakes that are probable to manifest at the wind turbine set up site..

Keyword: - Beam1, Static Analysis 2, Dynamic Analysis 3, Natural Frequencies 4.

1. INTRODUCTION

The introduction of twist generally complicates the analysis of wind turbines. The twist will make it difficult or impossible to find axes for which the bending deflections are decoupled. However, the moments of inertia need solely be calculated once. They can then be transformed by using rotation into the right orientation. At this point, the analysis requires the solution of the coupled bending equations and the coupled bending stress equations.

The introduction of taper requires that the moments of inertia be computed at each station of interest. The equations which ought to be solved are then the identical as in the case of a beam of rectangular sketch shape with twist. If the rotor blades are constructed of greater than one material, for example aluminum and fiberglass or fiberglass of two or extra distinct bending moduli , it is fundamental that the so-called modulus weighted part be computed. This is a technique by way of which the tensile residences of the specific aspects of every cross-section are weighted in n the accumulation of those quantities crucial for analysis. For example, the modulus weighted x and y centroid locations define the place of the tension center for the cross-section. (The tension's center is that factor at which a utilized radial load offers no lateral deflections) The blades on the WF-1 are just such non-homogeneous, twisted, and tapered beams. The answer of the bending and stress equations requires the incorporation of numerical methods in n some algorithms.

1.2 Description of Load

Gravitational centrifugal forces are mass established which is usually concept to amplify cubically with growing turbine diameter [38]. Therefore, generators below 10 meters diameter have negligible inertial loads, which are marginal for 20 meters upward, and critical for 70 meter rotors and above [4]. The gravitational force is defined really as mass improved with the aid of the gravitational constant, though its path remains constant acting towards the center of the earth which causes an alternating cyclic load case. The centrifugal force is a product of rotational pace squared and mass and constantly acts radial outward, consequently the increased load needs of greater tip

speeds. Centrifugal and gravitational loads are superimposed to give a positively displaced alternating situation with a wavelength equal to one blade revolution.

1.3 Other Dynamic Considerations

Gravitational centrifugal forces are mass dependent which is generally concept to extend cubically with increasing turbine diameter [38]. Therefore, mills under ten meters diameter have negligible inertial loads, which are marginal for 20 meters upward, and indispensable for 70 meter rotors and above [4]. The gravitational pressure is defined simply as mass extended by the gravitational constant, even though its path remains consistent acting in the direction of the core of the earth which reasons an alternating cyclic load case. The centrifugal force is a product of rotational speed squared and mass and constantly acts radial outward, subsequently the multiplied load demands of greater tip speeds. Centrifugal and gravitational masses are superimposed to supply a positively displaced alternating situation with a wavelength equal to one blade revolution.

1.4 Environmental Effects

As with all energy provide options, wind strength can have unfavorable environmental impacts, such as the attainable to reduce, fragment, or degrade habitat for wildlife, fish, and plants. Furthermore, spinning turbine blades can pose a threat to flying natural world like birds and bats. Due to the manageable affect that wind power can have on wildlife, and the manageable for these problems to delay or avert wind development in great wind aid areas, addressing influence minimization, siting, and permitting problems are amongst the wind industry's absolute best priorities.

To address these troubles and assist environmentally sustainable development of wind strength in the India, G.E (GENERAL ELECTRIC) invests in projects that are seeking for to represent and recognize the influence of wind on wildlife both on land and offshore. Furthermore, G.E (GENERAL ELECTRIC) invests in things to do to gather and disseminate scientifically rigorous peer-reviewed lookup on environmental influences via centralized data hubs such as Tethys. The workplace additionally invests in scientific research that allows the innovation and improvement of good value technologies that can decrease flora and fauna affects at land-based and offshore wind farms.

1.5 Motivation and goals of cutting-edge research

The important objective of the find out about is to address the geometric and material non-linear consequences that end result from the extreme hundreds that a wind turbine is subjected underneath the failure loads. This is a usual problem in the restrict nation plan for failure loads, the place the evaluation is normally elastic, whilst the sketch is inelastic and is based totally on cross-sectional closing strength. This method is acceptable (although no longer necessarily efficient) in building design, the place the structures are distinctly redundant. Redundancy lets in the excessive load capability to strengthen via internal pressure redistribution (Conniff, D. E. and Kiousis, P. D.(2007). However, wind turbine towers are statically determinate and can't redistribute their inner forces. Instead, the nonlinear response of a cross-section influences the natural frequency of the structure and its response to the dynamic loads. Thus, pressure improvement and viable dynamic resonance need to be identified extra exactly to diagram safely for dynamic wind and seismic loads. Such accuracy upgrades are big each for the dynamic analysis of the towers, which are currently performed by the turbine manufactures, ignoring inelastic behavior, and the quasistatic evaluation of the foundations which are performed by way of project structural and geotechnical engineers based on loads that are furnished by means of the turbine manufactures.

1.6 Scope of this research

This study makes use of the Embarcadero's Delphi, which is a Windows primarily based Object Pascal programming environment to enhance a novel finite element evaluation in order to complete the following tasks:

1- Develop the non-linear moment-curvature relation for cross-sections manufactured using steel.

2- Implement non-linear moment- curvature relations for shallow foundations, which are the most common types of foundations for on-land turbines.

3- Develop the linear and nonlinear structural models of wind turbine towers which include nearby and global instability (i.e. buckling) effects.

4- Develop a collection of arbitrary wind and seismic excitations to strengthen response envelopes.

5- Use the above criteria to layout wind turbine towers.

2. STRESS AND DETECTION

In the absence of torsional load (moment round the beam axis), the B33 element used in the tower does now not output the shear stress, S12. Therefore, Mises stress, S; Mises, is the same as S11 in magnitude. We regarded at the axial stress, S11, for this case. As proven in Figure 2.1, the most axial stress, S11, of the tower due to the bending moment used to be about 248.211 MPa, giving element of security of 1.4 using the material's yield power of 344.738 MPa. As shown in Figure 7.2, the most detection in the bad x-direction, U1, was once about 863.6 mm at the tower tip.

2.1 Section Force and Section Bending Moment

The section force, SF1, is the axial force at the beam issue nodes (1 denotes beam's axial direction in this case), and the part moment, SM2, is the bending moment with admire to beam's neighborhood y-axis (2-axis, pointing out of the paper in this case). They have been reviewed at each area of the tower (Figure 2.2). The effects were used as the sketch hundreds for the specific components such as bolts, lugs, welds and angels. The largest bending stress used to be 11.67 Nm which was once found just above the strut attachment. This location also corresponds to the greatest axial stress as considered in Figure 7.2. The axial forces for the strut were about 75619.7672 N in tension and 55157.94784N for the ginpole in compression.

2.1.1Reaction Forces

The response forces had been reviewed at the tower's support locations: bearings and the anchor plate. The outcomes supply design hundreds for the basis and the anchor bolts.

For the tilt-up load case, the response forces, RF, had been calculated as shown in Figure 2.2.

2.1.2 Result Plots







Figure 2.2: Section Axial Force, SF1 (top) in Kgf, and Section Moment

2.2 Load Case: Maximum Thrust and Gravity

The 9341.265N of maximum thrust calculated in Chapter four used to be determined to be the worst load case for the tower among others considered. The thrust load used to be applied in two directions, x-, and y-direction, as proven in Figure 2.2. The prevailing wind direction is the x-direction. Although the probability of the most thrust applied in the y-direction used to be low at this site, it used to be considered for the analysis. The gravitational load was applied in the terrible z-direction for the entire physique as well. The identical conventional assumptions have been utilized as listed for this analysis.



Figure 2.3: Load Case: 2k kgf Maximum Thrust

2.3 Results for Thrust Load Applied to x-Direction

(a)Stress and Defection

For this load case, the effects produced similar degrees of stress and deection as the preceding load case, the installation case. As shown in Figure 2.3, the most axial stress of the tower was once located to be little over 248.211 MPa which gives the component of security of 1.4 on yield. The deection at the tip was once about forty inches. The normal size of the tower is 21336 mm, so the detection is small, accounting for only four p.c of the normal tower length.

(b)Section Axial Force and Section Bending Moment

The axial force and the bending second of the tower have been reviewed simply as the preceding load case. The biggest bending moment of was once 11.98 Nm which was found simply above the strut attachment. The second in this load case used to be a little bit decrease than the set up case. The axial pressure for the strut was about 10 kips in compression, and 29892.05N in tension for the strut. These results matched well with the static hand calculations as proven.

(c)Reaction Forces

At assist locations, bearings (2X) and the anchor plate, the response forces have been calculated. The two bearing reaction forces were identical. For a bearing, the base shear pressure (horizontal or x-direction) was once 1050 lbf, and pull-out force (vertical or z-direction) was once 1500 lbf as proven in Figure 2.4. For the anchor plate, the complete reactions had been calculated to be about 7600 lbf in z-direction, which is compressive force applied to the foundation. The direction of the pull-out force and the compressive pressure may additionally be reversed for the wind blowing from the contrary direction.



Figure 2.4: Axial Stress, S11 in psi and Deection, U1 in inches for Thrust Applied to x-Direction



Figure 2.5: Section Axial Force, SF1 (left) in lbf, and Section Moment.

2.4 Results for Thrust Load Applied to y-Direction

(a) Stress and Deection

Figure 2.5 shows the axial stress, S11, and the corresponding deection in the y direction, U2, of the tower. The maximum stress on the tower used to be about 38 ksi at the lower phase of the tower, and the greatest deection used to be about sixty nine inches at the pinnacle of the tower. The stress distribution along the tower mast appears fairly uniform due to the tapered cross-section. The resulted stress has the factor of protection of 1.3 to yield, and the deection is about 8% of the overall tower length.

As seen in Figure 6.11, a small amount of torsional loads, SM3, had been found on the strut, ginpole and decrease phase of the tower for this load case (presumably due to the hinge constraints imposed on the strut, ginpole and their attachment factors of the tower which are subjected to a moderate rotation with respect to one of the "tied" rotational axes). The resulting shear stress, S12, was small compared to the axial stress, S11 (1:58 ksi Vs. 38 ksi). Therefore, it did no longer have a significantly effect on the common mixed stress, S; Mises as proven in Figure 6.12. Therefore, looking at S11 rather of S;Mises is lifelike as well.

(b) Section Axial Force and Section Bending Moment

There used to be no significantly axial force contribution in the structure for this load case. However, the bending moment on the tower was once large. As proven in Figure 2.6, the biggest bending second with recognize to beam's 1-axis (global x-axis) was once 1:72 _ 106 in - lbf at the base of tower mast. Note that the rainbow stick-measure in this plot represents each beam's local 1-axis.

(c)Reaction Forces

This load case produced the greatest load at the important bearing assist places (Figure 2.6). The bearing located upwind of the tower prompted the pull-out force of 27:5 kips while the other bearing brought on 31:7 kips of compressive force and 2:1 kips of the base shear force. The anchor plate had marginal response forces compared to the one at the bearings.

	2005	
	100000	

Figure 2.6: Axial Stress, S11 in psi (Left), and Deection in y-direction

3. CONCLUSION

In the dynamic analysis, damping is a vital issue to a structure's response It is referred to as the soil-structure interplay (SSI). It is modeled the use of the spring, damper component at the foundation-soil interface; and the mass of the basis and section of soil are also covered assuming that the soil strikes in segment with the foundation.

Additionally, inclusion of an easy finite element mannequin that represents the wind turbine the usage of the beam elements could help improve the finite aspect mannequin too.

REFERENCES

[1] The European Wind Energy Association, \Economics of wind," in Wind Energy, The Facts (WindFacts), 2009.

[2] D. Malcolm, \Windpact rotor design study: hybrid tower design," tech. rep., National Renewable Energy Laboratory (NREL), April 2004.

[3] International Electro technical Commission (IEC), \homepage." http://www.iec.ch.

[4] International Electro technical Commission (IEC) Technical Committee 88: Wind Turbines, International Standard IEC61400-2, Wind turbines, Part 2: Design requirements for small wind turbines. IEC, 2nd ed., 2006.

[5] The European Wind Energy Association, \Technology," in Wind Energy, The

Facts (WindFacts), 2009.

[6] K. S. Dahl and P. Fuglsang, \Riso-r-1024 (en): Design of the wind turbine airfoil family riso-a-xx," tech. rep., Riso National Laboratory, December 1998.

[7] Ginlong Technologies, Wind Turbine Permanent Magnet Generator/ Alternator

Ginlong Technologies GL-PMG-3500.

[8] A. Martinez, F. Martinez, D. Nevarez, and Z. Taylor, \Wind turbine nacelle

senior project." Cal Poly, San Luis Obispo, 2009.127

[9] B. Edwards, \Composite manufacturing of small wind turbine blades," Master's

thesis, Cal Poly, San Luis Obispo, 2009.

[10] F. Knox and A. Valverde, \Wind turbine foundation design." Cal Poly, San Luis Obispo, 2010.

[11] J. Manwell, J. McGowan, and A. Rogers, Wind Energy Explained: Theory, de-sign, and application, ch. 6 Wind Turbine Design. John Wiley Sons Ltd., 2nd ed., 2009.

[12] B. A. Babcock and K. E. Conover, \Design of cost-e_ective towers for an advanced wind turbine," Wind Energy, vol. 15, 1994.

[13] P. Gipe, \Wind turbine tower trends."

[14] Det Norske Veritas, Riso National Laboratory, Guidelines for Design of Wind

Turbines, 2nd ed., 2002.

[15] L. Global Energy Concepts, \Windpact turbine design scaling studies technical area 3 - self-erecting tower and nacelle feasibility," tech. rep., National Renewable Energy Laboratory (NREL), March 2001.

[16] A. Huskey and D. Prascher, \Validation of aero elastic model of nordtank 500/37," tech. rep., Riso National Laboratory, November 1997.

[17] G. C. Larsen and P. Volund, \Validation of aero elastic model of vestas v39,"

tech. rep., Riso National Laboratory, April 1998.

[18] A. Huskey and D. Prascher, \Tower design load verification on a 1-kw wind

turbine, tech.rep" National Renewable Energy Laboratory (NREL), January 2005.

[19] Dassault Systemes, Abaqus Analysis User's Manual, 2009.

[20] B. S. Taranath, Wind and Earthquake Resistant Buildings: Structural Analysis and Design, ch. 2 Seismic Designs. Marcel Dekker, 1st ed., 2005.

[21] Bellcore, Network Equipment-Building System (NEBS) Requirements: Physical Protection (GR-63-Core, section 5), 1995.

[22] E. Wilson, \Dynamic analysis using response spectrum seismic loading," CSI

Tech Report, vol. 15, 1994.

[23] Strand7, Use of Damping in Dynamic Analysis, 2011.

[24] I. Prowell and P. Veers, \Assessment of wind turbine seismic risk: Existing literature and simple study of tower moment demand," tech. rep., Sandia National

Laboratories, March 2009.

[25] International Electro technical Commission (IEC) Technical Committee 88: Wind Turbines, International Standard IEC61400-1, Wind turbines, Part 1: Design requirements. IEC, 3rd ed., 2007.

[26] R. D. Cook, Finite Element Modeling for Stress Analysis. John Wiley and Sons, Inc., 1995.

[27] N. Bazeos, G. Hatzigeorgiou, I. Hondros, H. Karamaneas, D. Karabalis, and

D. Beskos, \Static, seismic and stability analyses of a prototype wind turbine steel tower," Engineering Structures, vol. 24, 2002.

[28] R. Huston and H. Josephs, Practical Stress Analysis in Engineering Design,

ch. 20 Flanges. CRC Press, 3rd ed., 2009.