

Real-Time Drowsiness Monitoring System for Safer Driving

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Abstract—

In order to prevent traffic accidents, the review paper "Real-Time Driver Depression Monitoring for Accident Prevention in Smart Vehicles" focuses on the creation of a system that can identify driver depression in real time. This method looks for indicators of depression in drivers by employing facial expression recognition technology that has been improved by transfer learning using the VGG-16 model. The algorithm uses face analysis to identify behavioral signs of depression by using a library of photos showing drivers in both normal and sad conditions.

In order to lessen the possibility of accidents brought on by intoxicated driving, the system safely transfers control of the car from the driver to the automated driving systems when it detects depressive symptoms. With a 96% accuracy rate, 98% precision rate, 97% recall rate, and 97% F1-score, the model demonstrated its ability to improve road safety in smart car applications.

I. INTRODUCTION

Depression's pervasive effects on people's quality of life and the dangers it poses to driving safety are highlighted in the paper's opening.

Millions of people worldwide suffer from depression, which manifests as mood swings, difficulty concentrating, and exhaustion. As per the World Health Organization (WHO), depression is a major contributor to disability, affecting over 264 million people, and is predicted to emerge as one of the most prevalent illnesses globally. For drivers, this condition is especially concerning because it affects vital driving skills including decision-making and reaction times, which raises the likelihood of accidents. The use of Vehicular Ad-hoc Networks (VANETs) to increase road safety by allowing cars to interact with infrastructure and one another to provide vital information is examined in this study. Traffic safety and efficiency are greatly improved by such systems, particularly when combined with technology that track the mental health of drivers. Real-time facial expression analysis might be used to identify driver despair, allowing smart cars to instantly start safe driving interventions. This integration emphasizes how crucial it is for vehicle safety systems to address mental health issues in order to lower the risk of accidents. Depression is a serious mental health condition that affects millions of people worldwide. It impairs drivers' ability to focus and make decisions.

Recognizing depression symptoms early on can increase road safety because a significant portion of accidents are caused by drivers who are impaired. The study suggests employing sophisticated machine learning models to track drivers' emotional states and provides a solution by handing over control to automated systems in smart cars.

1.1. Preliminaries

The study emphasizes the severe consequences depression, a serious mental health illness that affects millions of people worldwide, has on a person's cognitive and physical capacities, especially when it comes to activities like driving that call for attention and fast decision-making. Depression symptoms, such as chronic melancholy, exhaustion, decreased attention, and slowed reaction time, can have a direct impact on a driver's capacity to maintain road focus and react appropriately to unexpected situations, like pedestrian crossings or sudden stops by other cars. Such disabilities increase the likelihood of collisions, presenting a serious risk to other drivers, passengers, and pedestrians in addition to the injured driver.

A. Use of VANETs in Monitoring Systems:

Vehicles and roadside infrastructure, such traffic signals and emergency response systems, can communicate in real time thanks to

specialized mobile networks called vehicular ad hoc networks, or VANETs. When it comes to driver monitoring systems, VANETs offer a vital platform for sharing vital data regarding environmental conditions, traffic patterns, and driver conditions, including possible mental health problems like depression. VANETs can swiftly communicate with neighboring cars and traffic control centers when a vehicle identifies symptoms of driver melancholy using in-car sensors, facial recognition, or physiological data.

B. Development of a Real-Time Depression Monitoring System:

Using OpenCV and the VGG-16 model for facial expression detection, a real-time depression monitoring system is developed. Known for its efficiency and simplicity, the VGG-16 design is optimized for the depression detection task. As a training and validation dataset, 6,500 photos classified as "Depressed" and "Normal" are employed.

Model performance is improved and consistency is ensured by preprocessing procedures like normalization, Gaussian blur noise reduction, and scaling images to 224x224 dimensions. The accuracy of the model is assessed by separating the images into training (70%) and testing (30%) groups.

Through frame-by-frame processing of video streams, OpenCV makes the system dynamic and responsive, allowing for real-time video analysis. The technology recognizes facial expressions associated with depression and initiates treatments to improve vehicle safety.

C. Integration into Vehicle Automation:

Based on the driver's condition, intelligent control transfer is made possible by the integration of the depression monitoring system with vehicle automation. Through facial expression analysis, the system detects indicators of sadness and initiates a smooth transition of control from the driver to the autonomous systems of the car.

By reducing the dangers of impaired driving, like poor decision-making or delayed reaction times, this feature improves safety. In order to transfer control, longitudinal control must be turned on for speed modification, lateral control for lane position maintenance, and sequence control for traffic optimization. When it comes to crucial situations, this automation makes sure the car runs securely without depending on the driver's input.

1.2. Performance highlights:

With an impressive 96% accuracy and 97% recall, the suggested depression monitoring method performs exceptionally well.

These measurements highlight the accuracy and dependability of the VGG-16-based model in identifying depression from facial expressions. Safety-critical applications such as driver monitoring depend on the system's ability to detect true positive cases with low false negatives. A major factor in these outcomes is the VGG-16 model's fine-tuning and the datasets' thorough preprocessing. By improving vehicle safety and lowering the likelihood of accidents involving intoxicated drivers, this performance guarantees the system's dependability in real-world situations.

Using facial expressions as trustworthy emotional markers, the study expands on earlier work in affective computing and transfer learning theory. Previous research has demonstrated a strong relationship between certain facial expressions and mental health conditions including depression. Niedenthal et al. famously showed brain connections between facial expressions and depressed symptoms, confirming the method's efficacy. A basis for the

application of facial expression analysis in driver monitoring systems has been established by its successful application in emotion recognition tasks. More complex models, such as CNNs and ResNet50, have been investigated for comparable applications and have demonstrated impressive performance results.

The accuracy, precision, and recall of the VGG-16 model employed in this investigation, however, are superior to these. Additionally, the report cites developments in deep learning techniques, such as transfer learning, to effectively handle small datasets. The system delivers state-of-the-art performance by integrating VGG-16 with real-time capabilities utilizing OpenCV. By concentrating on depression detection for smart car integration, the method fills in the gaps in previous research. This study is a major step toward using deep learning to improve psychological monitoring and driver safety.

1.2.1 Model Methodology Expanded The dataset used by the algorithm consists of 6,500 annotated photos that have been divided into "Depressed" and "Normal" states. To meet the input specifications of the VGG-16 model, images are preprocessed by scaling them to a constant resolution of 224x224 pixels. By ensuring consistent pixel intensity values, normalization facilitates quicker and more precise model training. Rotation, flipping, and scaling are examples of data augmentation techniques used to increase dataset diversity and decrease overfitting. To make sure the model is assessed on unknown data, a 70-30 split is employed for training and testing. By using its pre-trained weights, the VGG-16 model is optimized for depression detection while reducing its need on extensive labeled datasets. The model effectively differentiates between the "Depressed" and "Normal" categories by concentrating on feature extraction from facial expressions. Real-time frame-by-frame analysis is made possible by the integration of OpenCV for processing video sources. Continuous driver behavior monitoring is ensured by treating each frame as a distinct image for detection.

1.2.2 Control Mechanism

When the system detects driver sadness, an intelligent control transfer mechanism kicks in. Vehicle speed is adjusted by longitudinal control, lane alignment is guaranteed by lateral control, and traffic behavior is optimized by sequence control. When a driver is impaired, these features allow autonomous car systems to take over with ease and guarantee safe operation. Road safety is improved by this technique, which also complies with current autonomous vehicle criteria for intelligent intervention.

CONCLUSION:

In the context of Vehicular Ad-hoc Networks (VANETs), the study presents a deep learning model for the real-time detection of depression in drivers. The model achieves excellent detection accuracy by using facial emotion data with the VGG-16 architecture. The findings show that the accuracy rate is 96%, and the precision, recall, and F1-scores are 98%, 97%, and 97%, respectively.

When indicators of driver melancholy are identified, the system enables control transfers and early warning systems to increase road safety. The results show that deep learning approaches are good in detecting depression and might be integrated into intelligent vehicle systems. The study does, however, acknowledge constraints such as dataset specificity and the variability of real-world situations, indicating that larger datasets and multimodal data integration should be improved. The suggested model outperforms alternative approaches such as ResNet50 and can be used in conjunction with technologies like as GPS and telemetry to track driver states comprehensively. By addressing psychological variables, this study makes a substantial contribution to smart car safety and develops proactive accident prevention techniques.

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