Robotics Grape Farming

GhangurdeYogita Chhagan[1], More Rupali Rajendra[2], Date Shraddha Keshav[3], Rakhibe Gauri Kiran[4]
[1,2,3,4]*U.G.Student, Department of Computer Engineering, Nashik, India*

Abstract

The venture has a robot that utilizes the vision base column direction strategy to pass through the line crops. Eventually, a novel framework has been portrayed for Plant and Food Research which utilizes a few electrical and PC frameworks designing speculations. A model mechanical arm needs to Robotics and mechanization (R&A) can assume a huge part in the public arena to meet its future farming creation needs. For sixty years, robots have assumed a basic function in expanding effectiveness and lessening the expense of modern creation and items. All the more as of late, ranchers have begun to explore different avenues regarding frameworks that robotize or expand tasks, for example, pruning, diminishing, and reaping, just as cutting, splashing, and which ought to be coordinated with engines, controllable utilizing explicit electronic segments and custom PC programming. A few sensors are incorporated into the mechanical framework including shading, temperature, and mugginess frameworks. The framework required the utilization of vision, with custom calculations being created to recognize the leaf shade of the plant and distinguish the sickness. The whole framework will coordinate into a completely mechanized bundle. This gives the possibility to plant supplement levels and the quick climate to be regularly changed in light of constant detecting bringing about improved fast development with negligible human info

Keywords: *spraying fertilizers, IP Camera*

I. INTRODUCTION

Current ranches are hope to create more yields with higher caliber at lower costs in a feasible manner that is less reliant on the workforce. Usage of computerized cultivating and site-explicit exactness the board are a portion of the potential reactions to this desire, which depends on the sensor innovation as well as the nonstop assortment of field information that is just possible through appropriate use of rural robots. Horticultural field robots and controllers have become a significant part in various parts of advanced cultivating and exactness farming. With the advances in controls hypothesis, uses of these robots in computerized cultivating have indicated developing revenue towards robotization, changing the conventional field activists to cutting edge modern assignments that are drawing in speculators, proficient architects, and organizations. Robot route dependent on visual recognition frameworks, (for example, installed camera frameworks) has been particularly pervasive throughout the most recent thirty years. These frameworks are vigorous and solid as they give point by point data about the climate, which might be neglect by different kinds of sensors. In current cultivating applications, so various sorts of computerization methods are use for simple and staff less tasks that incorporates the significant capacities like cultivating and splashing manures. To follow the right water system technique, grape water prerequisites and supplement necessities ought to be known. The framework utilizes so numerous programmed strategies, which require less work. The undertaking expects to build up a model of an independent agrarian robot that incorporates a mechanize direction framework, will be controlled from android versatile application, visual investigation utilizing IP Camera, and hindrance discovery framework .

II. LITERATURE SURVEY

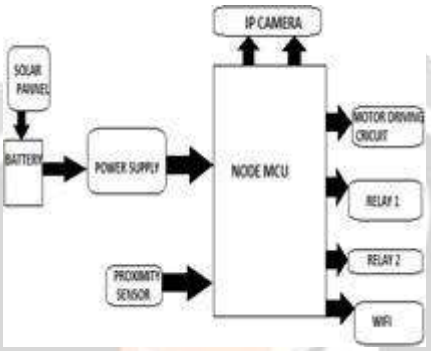
Redmond RaminShamshiri, Cornelia Weltzien, Ibrahim A. Hameed, Ian J. Yule, Tony E. Grift, Siva K. Balasundram, LenkaPitonakova, Desa Ahmad, Girish Chowdhary had given the data about rural robot in their examination paper "Innovative work in rural mechanical technology: A viewpoint of computerized cultivating" which routed to Object distinguishing proof, task arranging calculations, digitalization and improvement of sensors are featured as a portion of the confronting difficulties with regards to advanced cultivating.. They had indicated an advancement of horticultural robots that can viably perform monotonous field assignments have filled fundamentally in the previous decade. It should be noticed that improvement of a moderate and compelling agribusiness robot requires a multidisciplinary coordinated effort in a few territories, for example, plant designing, software engineering, mechatronics, dynamic control, profound learning and smart frameworks, sensors and instrumentation, programming plan, framework mix, and yield the board.

For instance, in a shared gathering framework utilizing human-and-robot, any organic product that is missed by the robot vision will be spotted by the human on a touchscreen interface. On the other hand, the whole

robot detecting and acting component can be performed by a human administrator in a virtual climate. All things considered, a farming robot must be financially reasonable which implies it must detect quick, ascertain quick, and act quick to react to the fluctuation of the climate Dalia Marcela Rojas-Castro, Arnaud Revel, Michel Ménard recommended in their examination paper "Mechanical and Document Analysis Cross-Fertilization: Improving Place Cells Based Robot Navigation" that permits the robot to imitate human conduct in exploring inside an obscure structure by "perusing" a guide or a story plan with its camera and "recalling" a grouping of signs to follow in transit.

The robot can distinguish without anyone else what it considers to be pertinent from the climate as common milestones and learns them in that capacity. The uncertainty given by bunches with comparable descriptors is managed by the extra group position datawhich together are utilized to learn new places and remember them during robot route. The learning task is acted in a gradual manner permitting the robot to adjust to the climate. The model proposed by the creators can be infused into it to additionally create it concerning power and culmination.

III. FIGURES



1.1 IMPORTANCE

In rural areas, grape farming is done by traditional methods. The major problem and drawback is to maintain and protect the farm area. For that purpose, farmer always uses fertilizer and pesticides but it is a manual method and it requires manpower with a lot of hard-work. Also, the second alternative solution was to use a tractor for fertilization purpose. So, by using battery operated robot, farmers will be able to fertilize the grape farm in no-labor-cost, using renewable energy source, and fully automated system. The project possesses a robot which uses vision based row guidance method to drive through the row crops. Ultimately, a unique system has been described for Plant & Food Research which makes use of a number of electrical and computer systems engineering theories. A prototype robotic arm has to Robotics and automation (R&A) can play a significant role in society to meet its future agricultural production needs. For six decades, robots have played a fundamental role in increasing the efficiency and reducing the cost of industrial production and products. More recently, farmers have started to experiment with systems that automate or augment operations such as pruning, thinning, and harvesting, as well as mowing, spraying, and which should be integrated with motors, controllable using specific electronic components and custom computer software. A number of sensors are integrated into the robotic system including color, temperature and humidity systems. The system required the use of vision, with custom algorithms being developed to identify leaf color of plant and detect the disease. The entire system will integrated into a fully automated package. This provided the potential for plant nutrient levels and the immediate environment to be routinely adjusted in response to continuous sensing resulting in optimized rapid growth with minimal human input.Modern farms are expected to produce more yields with higher quality at lower expenses in a sustainable way that is less dependent on the labor force. Implementation of digital farming and site-specific precision management are some of the possible responses to

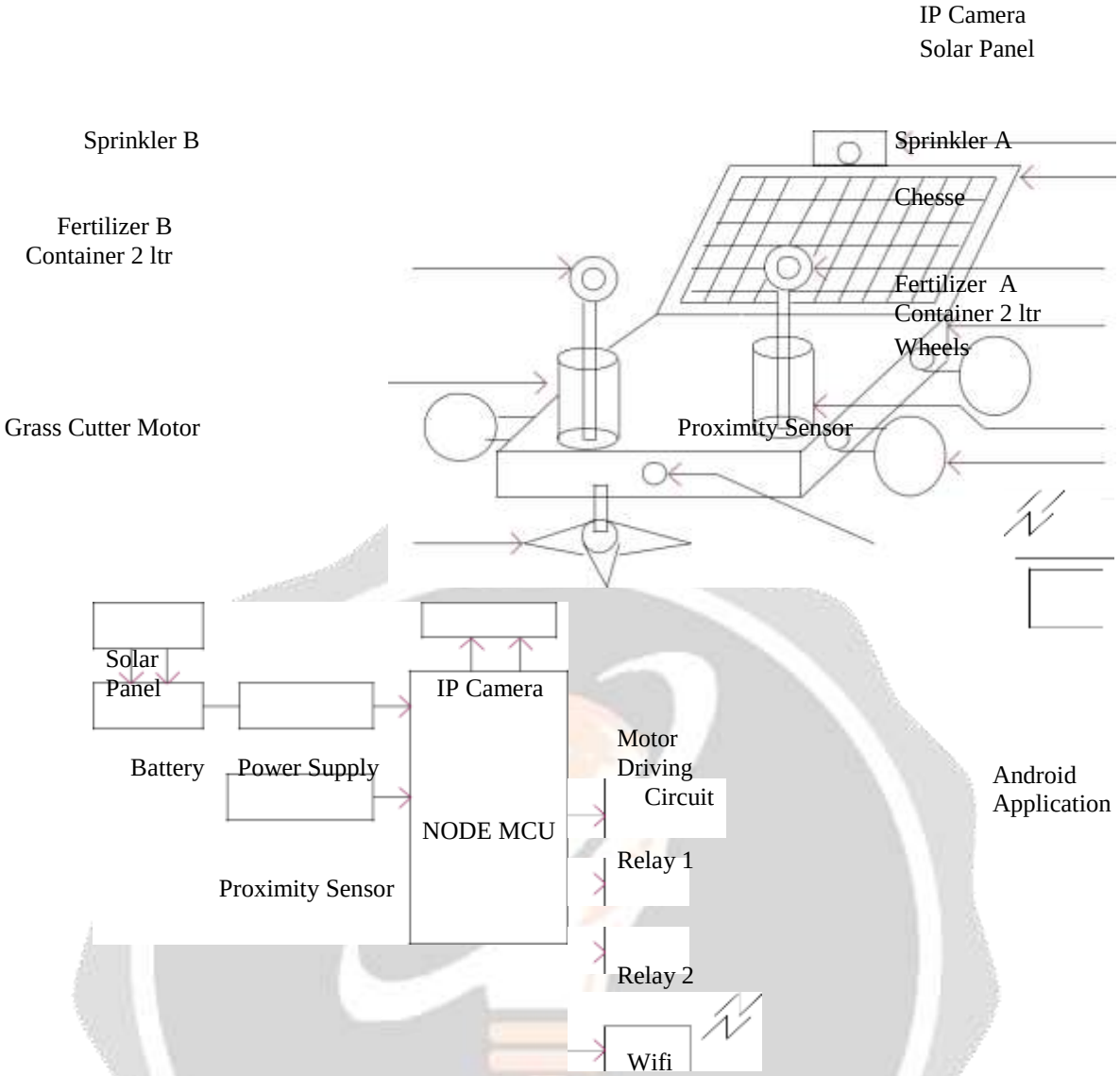
this expectation, which depends not only on the sensor technology but the continuous collection of field data that is only feasible through proper utilization of agricultural robots.

2 . OBJECTIVES

- To Develop a IOT based smart robot for grape farming.
- To minimize the efforts required to fertilize the grape farm.

3 .SYSTEM ARCHITECTURE

- In this project we are using latest technology internet of things (IoT) using is a node MCU microcontroller we will interface microcontroller with the Wi-Fi with the help of mobile or router hotspot so every internet user need SSID username and password for providing high security applications. We will also use the Android application for or controlling the fertilizer as per user selection input also control the robot. With the help of battery robot will work and we also develop battery charger for charging the battery the new thing. In this project we will introduce the artificial intelligence Technology with the help of proximity sensor it will change the obstacle or the human presence and applied at automatic brake without any programming and without any microcontroller.



4. METHODOLOGY USED

- **Arduino Based Bluetooth Controlled Robot**:

  The purpose of our research is to provide simpler robot's hardware architecture but with powerful computational platforms so that robot's designer can focus on their research and tests instead of Bluetooth connection infrastructure..

- **Zigbee based wireless Controlled Robot** :

  The implementation of ZigBee based wireless sensor networks in service robot intelligent space.

- **GSM based controlled Robot:**

  Based on this technology we further moved to design a system that acts as platform to receive messages which indeed are commands

- **Proposed system using IoT based robot:**

  In this project we are using latest technology internet of things (IoT) using is a node MCU microcontroller we will interface microcontroller with the Wi-Fi with the help of mobile or

router hotspot so every internet user need SSID username and password for providing high security applications.

5.SYSTEM REQUIRMENTS

5.1 HARDWARE REQUIREMENTS

Sr.no	Parameter	Description	Quantity
1.	Node MCU	This is a NodeMcu based on ESP8285 module.	1
2.	IP Camera	Used for live streaming.	2
3.	Proximity sensor	It will change the obstacle without any programming and without any microcontroller	1
4.	DC Gear Motor	DC Supply: 12 V RPM: 60 at 12 V	1
5.	L298 based motor driver	Integrated monolithic circuit in a 15- lead Multiwatt and Power SO20 packages	1
6.	Solar panel	12 Volt,10 Watt for battery charging	1

CONCLUSION

We have effectively contemplated Node MCU Microcontroller with interfacing of Wi-Fi innovation. Additionally , the prerequisites of equipment and programming required are considered. The general investigation of IoT based innovation with correlation of different gadgets is investigated. As IoT based innovation has numerous points of interest, for example, in-constructed wi-fi innovation, covers enormous reach and prudent and having enormous speed of correspondence**.**

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