

# ROUGH TERRAIN VEHICLE

Dr. A.P.Ninawe, Ankit Badki, Nikesh Thakre, Prasanna Dongre, Rohit Nagdeve, Sushil Mulekar,

Sanket Jagtap

K.D.K college of engineering Nagpur

## Abstract

*The need to develop a largely stable suspense system able of operating in multi terrain shells while keeping all the bus in contact with the ground. To design a medium that can cut terrains where the left and right rockers collectively climb different obstacles. To sustain a cock of over 50deg without tilting over the sideways*

## Introduction

The Rocker dread system is the suspense arrangement used in Mars rovers introduced for Mars Pathfinder and also used on Mars Exploration Rover (MER) and Mars Science Laboratory (MSL) operations. This dread can repel mechanical failures caused by the harsh terrain on MARS. The primary mechanical point of the Rocker Bogie design is its drive train simplicity, which is fulfilled by two rocker arms.

## LITERATURE REVIEW

Important of space disquisition can be divided into three orders a hunt to more understand our macrocosm, interest, and profitable eventuality in using natural coffers outside our earth, and the future, colonization of extra-terrestrial bodies. Likewise, utmost interest has been in our moon and blights. As these planetary bodies are close by, and have surroundings that are sociable enough for rovers, and potentially for unborn colorization.

All-terrain vehicles (ATVs) have come adding popular in numerous countries around the world, both for occupational use, as well as recreational use. With an increase in fashionability, and the force of heavier and more important machines on the request, major traumas and deaths from ATV use are growing enterprises for public health and injury prevention professionals. This review of the literature on ATVs will concentrate on the medium and patterns of ATV-related injuries, the challenges of injury forestallment, and the goods of legislation and regulations regarding ATV operation. The adding burden of injuries and the substantial profitable cost from ATV-related traumas and deaths calls for intensification of injury forestallment. Revision of threat factors, institution of regulations and legislation, and enforcement of those rules are important way for forestallment of ATV-related detriment.

## METHODOLOGY

As per the exploration it's find that the rocker dread system reduces the stir by half compared to other suspense systems because each of the dread's six bus has an independent medium for stir and in which the two frontal and two hinder bus have individual steering systems which allow the vehicle to turn in place as 0 degree turning rate. Every wheel also has thick cleats which provides grip for climbing in soft beach and scrabbling over jewels with ease. In order to overcome perpendicular handicap faces, the frontal bus are forced against the handicap by the centre and hinder bus which induce maximum needed necklace. The gyration of the frontal wheel also lifts the front of the vehicle over and over the handicap and handicap overhauled. Those bus which remain in the middle, is also pressed against the handicap by the hinder bus and pulled against the handicap by the front till the time it's lifted up and over. At last, the hinder wheel is pulled over the handicap by the frontal two bus due to applying pull force.

## DESIGN OF ROCKER BOGIE

The important factor in manufacturing of rocker dread medium is to determine the confines of rocker and dread liaison and angles between them. The lengths and angles of this medium can be changed as per demand. The end of this work is to manufacture the rocker dread medium which can overcome the obstacles of 150 mm height (likestones, Page 1 of 2 rustic blocks) and can climb over stairs of height 150 mm. Also another target is to climb any face at an angle of  $45^\circ$ . To achieve the below targets we had designed the rocker- dread model by assuming stair height 150 mm and length 370 mm. Using Pythagoras theorem, we plant the confines of the model. It have both angles of liaison are 900 and 450.A. Designcalculation.The ideal of the exploration work is stair climbing. To achieve proper stair climbing the confines of liaison should be proper. Assume the stair height and length 150 mm and 370 mm independently. To climb stairs with advanced stability, it's needed that only one brace of wheel should be in rising position at a time. Hence to find dimension of dread liaison, first brace of bus should be placed at vertical position means at the end of the rising as shown. And alternate brace should be placed just before the launch of rising. There should be some distance between perpendicular edge of stair and alternate brace of wheel to striking of bus.

## PROPOSED WORK

As modular exploration platform the rover developed by this design is designed specifically to grease unborn work. With the development in technology the rover can be used for surveillance purposes with the cameras installed on the rover and minimizing the size of the rover. With some developments like attaching arms to the rover. It can be made useful for the lemon diffusing team similar that it can be suitable to cut the cables for diffusing the lemon. By the development of a bigger model it can be used for transporting man and material through a rough terrain or handicap containing regions like stairs. We could develop it into a wheel president too. It can be shoot in denes, jungles or similar places where humans may face some peril. It can also be developed into low cost disquisition rover that could be shoot forcollecting information about the terrain of some elysian bodies.

## CONCLUSION

This design will try reaching nearly all of our design conditions, and in numerous felicitations exceeding original design pretensions. Likewise all factors, mechanical and electrical, will be completely tested as a completed system in real world field testing conditions to validate their success. Overall, primary estimates for the general compass, budget, and timeline, for the design will be nearly followed; with the exception if the design pretensions relatively over budget.

## REFERENCES

- Meghdari, H. N. Pishkenari, A. L. Gaskarimahalle, S. H. Mahboobi, and R. Karimi, "A novel approach for optimal design of a rover mechanism," *Journal of Intelligent and Robotic Systems*, vol. 44, no. 4, pp. 291–312, 2005.
- Hali Neves, "ATVs and Agriculture," *ACTA Scientifc Agriculture*, vol. II, no.10, p.22, 2018
- L. Gao, S. Liu, R. A. Dougal, "Dynamic Lithium-Ion Battery Model for System Simulation." *IEEE*
- T. J. Akai, *Applied Numerical Methods for Engineer*, Toronto: John Wiley & Sons, 1994.
- J. F. Giera, R. Wang, M. J. Kamper, *Axial Flux Permanent Magnet Brushless Machines*, Boston: Kluwer Academic, 2004.